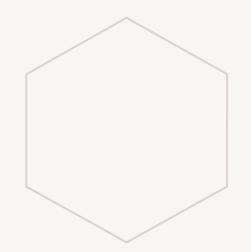
Cycle Path Condition Monitoring Techniques

Chase Fleeman, Michael Nieminen (ICC, Florida, USA)

ERPUG 2023 Athens, Greece October 27, 2023



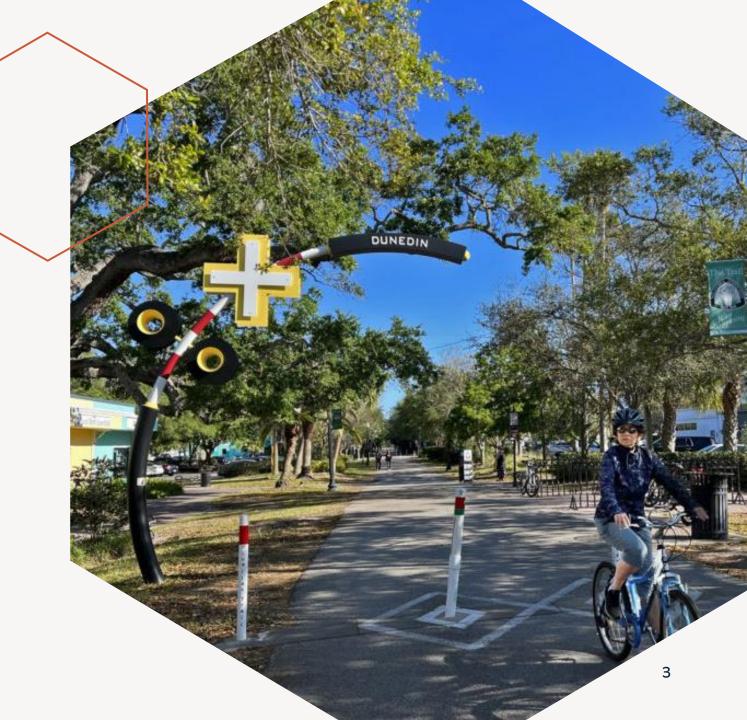
Agenda



Cycle Paths

In the USA and Canada, cycle paths are primarily used for recreational purposes.

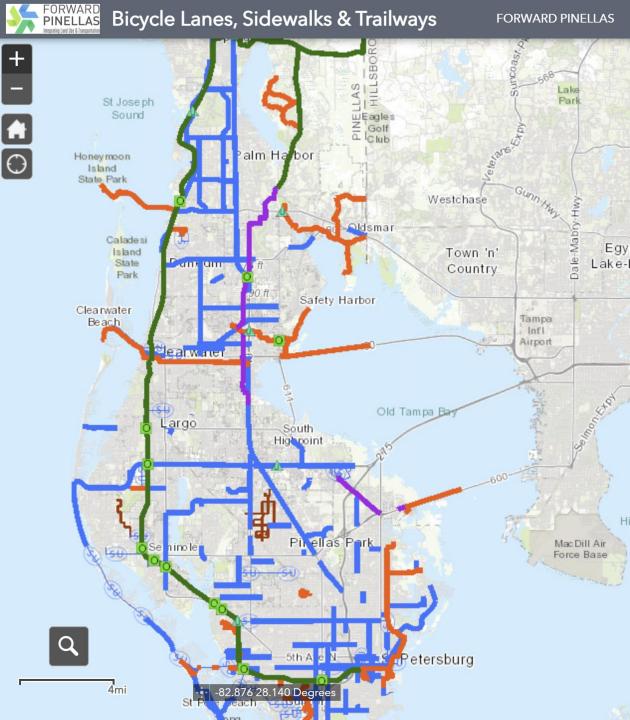
Condition monitoring and active management are required to ensure **safety** and **comfort** for users, as well as to **protect the investment**.



Florida Example

- The Pinellas Trail, built over an old rail line near Tampa, Florida, is **76 km** long.
- Uses: cycling, walking, and jogging.
- It is currently being extended to **121 km** (the project is about 60% complete)





Measurement Needs

- Faults and Tripping Hazards
- Obstructions and Protrusions (Trees, Poles, Vegetation, etc.)
- Gaps and Cracks
- Asphalt and Concrete Distresses
- Smoothness and Ride Quality



Sidewalk Surface Tester (SST)

- Introducing the new SST for sidewalk and • trail surveys
- Platform testing and selection •
- Designed and built in 2023 •
- Based on same Drive platform as ICC's Iris • family of collection vehicles









Vehicle Platform

- Trailerable, lightweight, narrow, 100% electric, golf-cart style vehicle
- Optimized for bicycle paths, walking trails, and sidewalks
- Length: 2.1 m
- Width: 1.0 m
- Mass: 220 kg
- Maximum Speed: 24 km/h
- Motor: 3000W 36V High Torque
- Vehicle Battery: Lithium Ion 36V, 60 Ah, 2160 Watt hours (Wh)
- Vehicle Run Time: 6-8 hours (per battery)
- Vehicle Charge Time: 4-6 hours
- Second Vehicle Battery included, drop-in field-replaceable
- System Battery: Lithium Ion 12V, 200 Ah, 2400 Watt hours (Wh)
- System Run Time: ~24 hours
- System Charge Time: 4-6 hours
- Passenger Capacity: 1



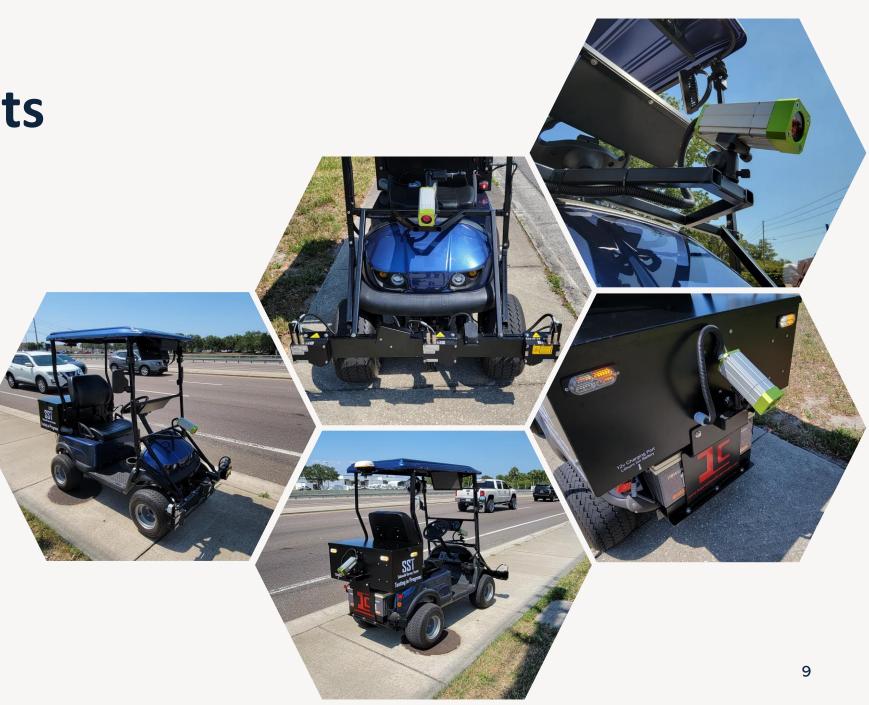
Subsystems

- 3x Gocator point lasers
- 2x 12MP Basler cameras (front and rear)
- 5g Accelerometers
- 250 Hz MEMS IMU
- Hemisphere DGPS
- 5,000 CPR wheel encoder
- Target sensor
- Drive collection system (fanless computer and ADAS in environmentally-sealed enclosure)
- High contrast monitor
- Event keyboard



Measurements

- Front and rear right-ofway images at 1.5 m intervals (captured at fixed interval)
- Laser Elevations at 0.5 or 1.0 mm longitudinal spacing (captured at fixed interval)
- Pitch, Heading, and Roll at 250 Hz
- All data synchronized to DMI and GPS to 0.0001 s (0.1 ms)



Measurements (cont.)

- Raw and high-pass filtered Longitudinal Profile data
 - Roughness parameters including International Roughness Index (IRI) and Rolling Straight Edge (RSE)
 - Texture parameters including Mean Profile Depth (MPD), Root Mean Square (RMS), and Ridge-Valley Depth (RVD)
 - Obstruction Height (e.g. Fault, Tripping Hazard)
 - Vertical Separation (e.g. Gap Width, Crack Width)
- Crossfall
- Grade

Further work is required to develop or adopt smoothness metrics that are suitable for characterizing safety and comfort on cycle paths and trails.



🕄 ICC Connect

Open Data Management View Reports Settings Help



- Longitudinal profile calculated from laser and accelerometer data (as in traditional inertial profiler) is insufficient
- Vehicle body motion is visible in the profile
- Accelerometer data processing is changed and supplemented with IMU data to subtract body motion from laser data
- The resulting HD profile is cleaner and can be used for further processing



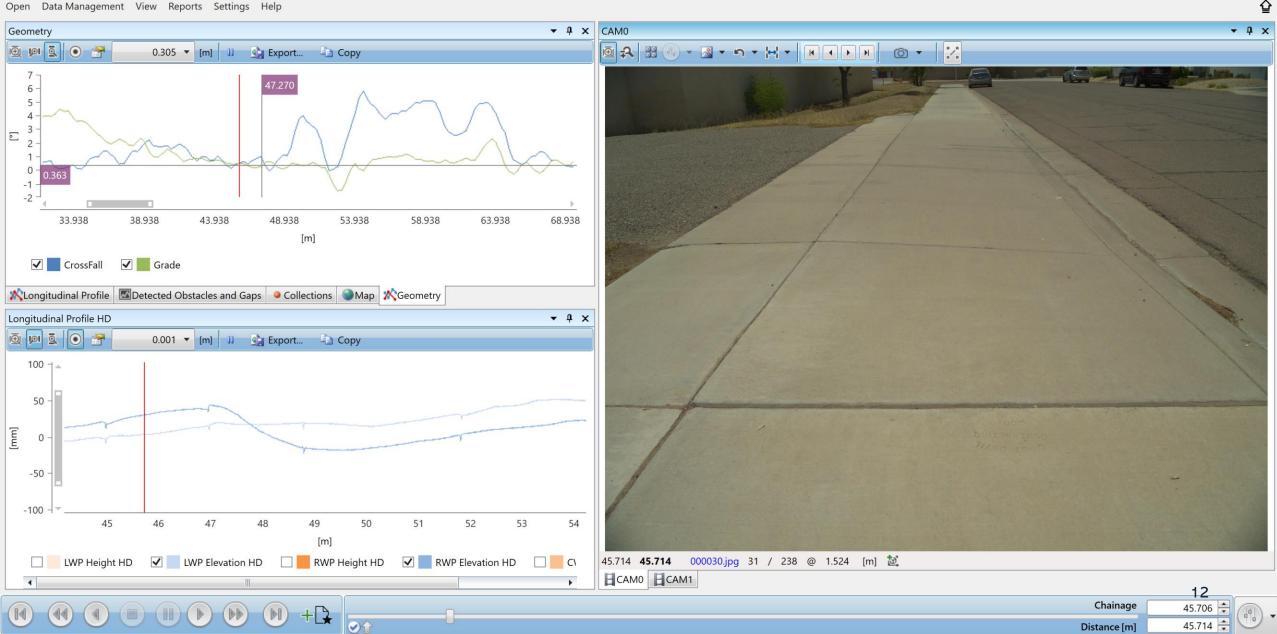
Crossfall and Grade

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Rec Connect

Open Data Management View Reports Settings Help



HD Profile shows Joints and Texture

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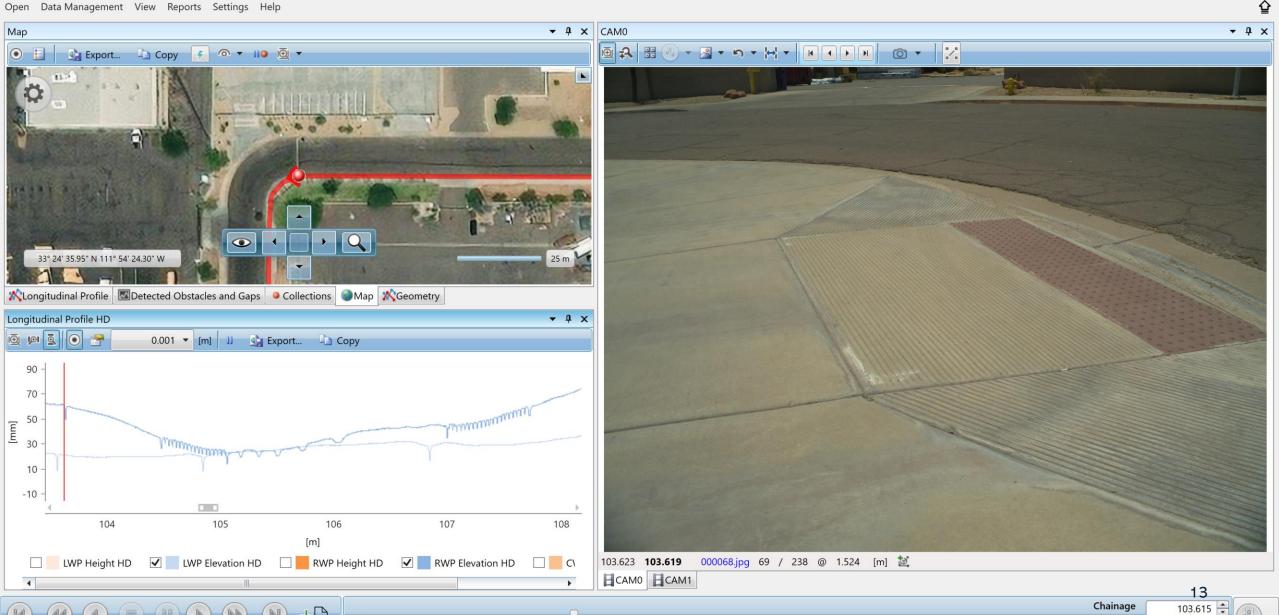
103.623

Distance [m]

X

Rec Connect

Open Data Management View Reports Settings Help

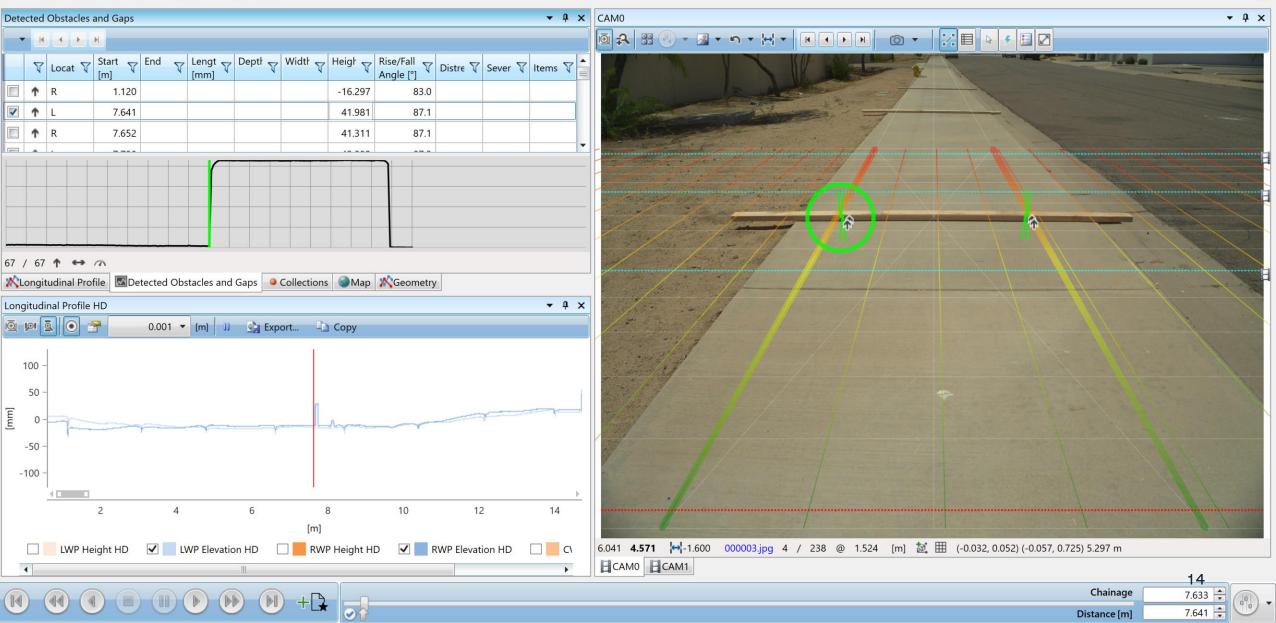


Obstacle and Tripping Hazard Detection

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🔍 ICC Connect

Open Data Management View Reports Settings Help



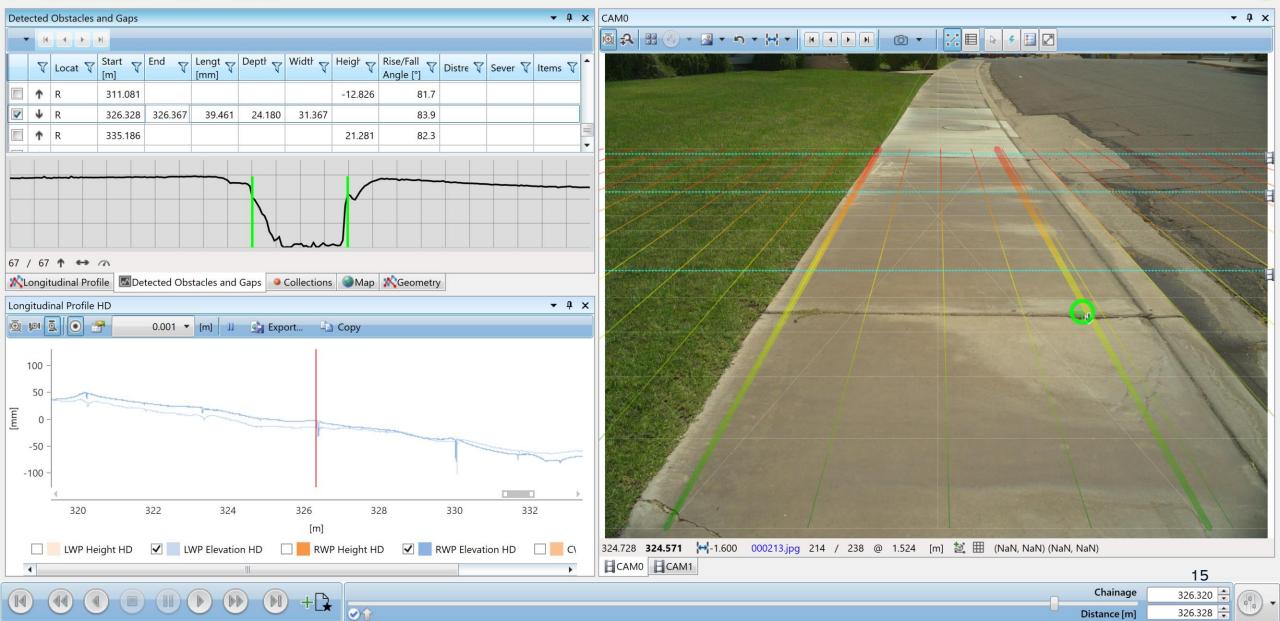
Gap Detection

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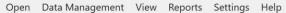
Reference to the second second

Open Data Management View Reports Settings Help

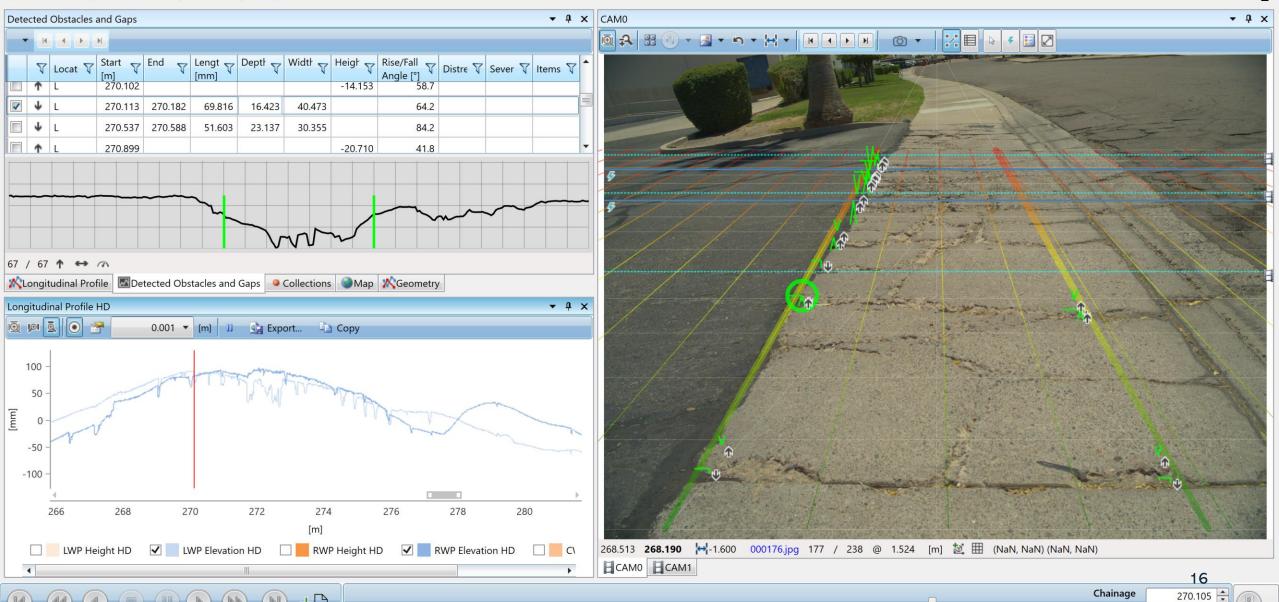


Highly Distressed Section

Rec Connect



1



270.113

Distance [m]

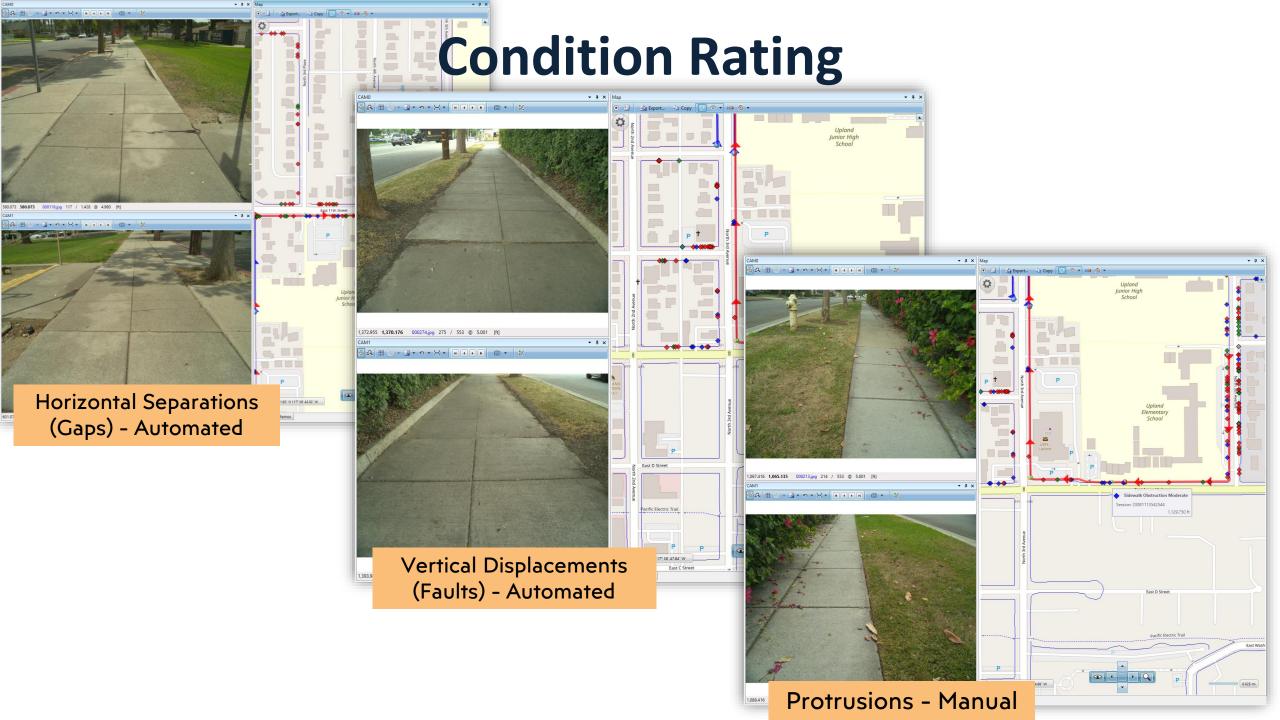
Custom Code Integration

8 Workflows...

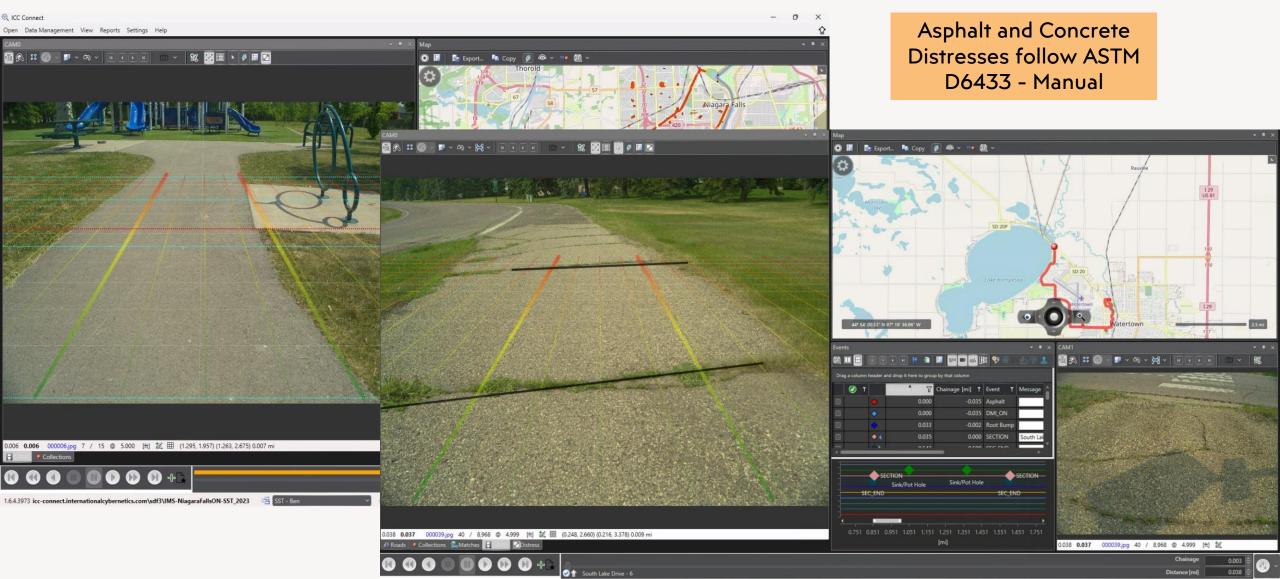
- New processing algorithms developed by agencies and research institutes can be put into production easily
- The Python integration in Connect[™] allows your code to be run alongside standard processors
- Your code has access to data via read/write API plus direct database access and raw data access
- Processor runs on one session at a time; batch processing is handled by the workflow engine

Selec	t Wo	orkf	low Obstacles and Gaps		•]	
¥₹ /	Add	Task	🗙 🗙 Remove Task 🛛 🏠 Move Up	Wove Up Move Down					
		#	Name	Description		Select 🛛 🏹			
		1	Obstacle Detection	the surface by analizing the			connect_python_processor_example.py		•
		2	Python Processor	needs to be placed in the Python subfolder of the installation path,		Destination Folde Python Path			

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Niagara Falls, Ontario, Canada



Typical Deliverables

- Condition Data GIS Layers
- Condition Index Calculation
- ArcGIS Dashboard or Story Map
- Easy Sidewalk Analysis (ESA)



Data Dictionary

• Distress survey produces PCI for each trail segment

Infrastructure Management				
City of Niagara Falls, Canada				
ony of Magara Falls, Callada				
Asset	Code	Asset Type	Measurement	Definition
Trail	TRA	Linear	Meters	An identification of the start and end of definable trail structures. If no structure exists, no entry will be made. Driveway ap same construction method is used beyond the driveway apron. Intersections will cause the structures to be interrupted, er intersection.
Attribute	Code	Reponses	Representation	Definition
TRA_SlabCount	Count slab)S	Numeric - Count	If material type is concrete, this point should be dropped for each slab to obtain the total slab count
TRA_Distress_Asphalt - Rutting	Asphalt - F	Rutting	Numeric - Area	Area quantity of rutting that is visible on asphalt trails
TRA_Distress_Asphalt - Longitudinal Cracking		ongitudinal Cracking	Numeric - Length	Length quantity of longitudinal cracking that is visible on asphalt trails
TRA_Distress_Asphalt - Transverse Cracking	Asphalt - T	ransverse Cracking	Numeric - Length	Length quantity of transverse cracking that is visible on asphalt trails
TRA_Distress_Asphalt - Alligator Cracking	Asphalt - A	Iligator Cracking	Numeric - Area	Area quantity of alligator cracking that is visible on asphalt trails
TRA_Distress_Asphalt - Block Cracking	Asphalt - E	Block Cracking	Numeric - Area	Area quantity of block cracking that is visible on asphalt trails
TRA Distress Asphalt - Edge Cracking	Asphalt - E	Edge Cracking	Numeric - Length	Length quantity of edge cracking that is visible on asphalt trails
TRA_Distress_Asphalt - Distortions	Asphalt - D	Distortions	Numeric - Area	Area quantity of distortions that are visible on asphalt trails
TRA_Distress_Asphalt - Bleeding	Asphalt - E	Bleeding	Numeric - Area	Area quantity of bleeding that is visible on asphalt trails
TRA_Distress_Asphalt - Raveling	Asphalt - F	Raveling	Numeric - Area	Area quantity of raveling that is visible on asphalt trails
TRA_Distress_Asphalt - Patching	Asphalt - F	Patching	Numeric - Area	Area quantity of patching that is visible on asphalt trails
TRA Distress Asphalt - Potholes	Asphalt - F	Potholes	Numeric - Count	Count of potholes that are visible on asphalt trails
TRA Distress Concrete - Linear Cracking	Concrete -	Linear Cracking	Numeric - Slab Count	Slab Count of linear cracking that is visible on concrete trails
TRA_Distress_Concrete - Divided Slab		Divided Slab	Numeric - Slab Count	Slab Count of divided slabs that are visible on concrete trails
TRA_Distress_Concrete - Corner Break	Concrete -	Corner Break	Numeric - Slab Count	Slab Count of corner breaks that are visible on concrete trails
TRA_Distress_Concrete - Joint Spalling	Concrete -	Joint Spalling	Numeric - Slab Count	Slab Count of joint spalling that is visible on concrete trails
TRA_Distress_Concrete - Faulting	Concrete -	Faulting	Numeric - Slab Count	Slab Count of faulting that is visible on concrete trails
TRA_Distress_Concrete - Polished Aggregate	Concrete -	Polished Aggregate	Numeric - Slab Count	Slab Count of polished aggregate that is visible on concrete trails
TRA_Distress_Concrete - Scaling	Concrete -		Numeric - Slab Count	Slab Count of scaling that is visible on concrete trails
TRA_Distress_Concrete - Patching	Concrete -	5	Numeric - Slab Count	Slab Count of patching that is visible on concrete trails
TRA_Distress_Concrete - Punchouts		Punchouts	Numeric - Slab Count	Slab Count of punchouts that are visible on concrete trails
			Task	

TRA_Severity

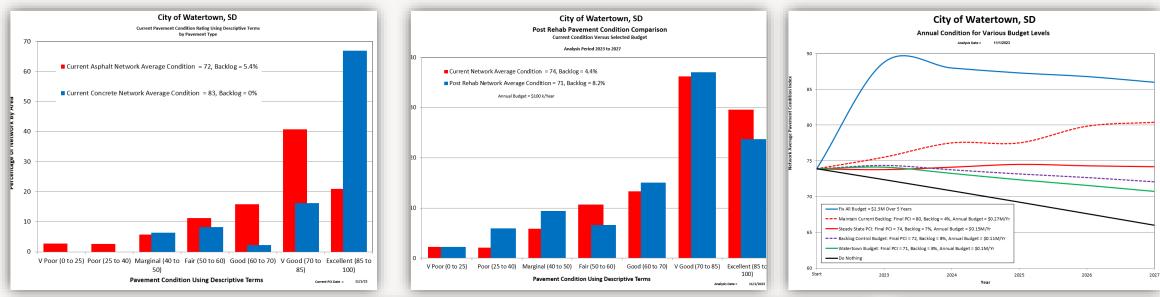
1 Moderate

Text

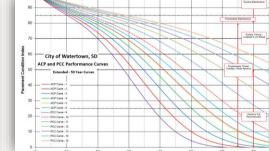
Severity observation for each LAD and Excessive Cross Slope - see SEVERITIES tab for details See Distress Severity tab for definitions

Easy Sidewalk Analysis (ESA)

Estimate Maintenance Costs and Plan Work

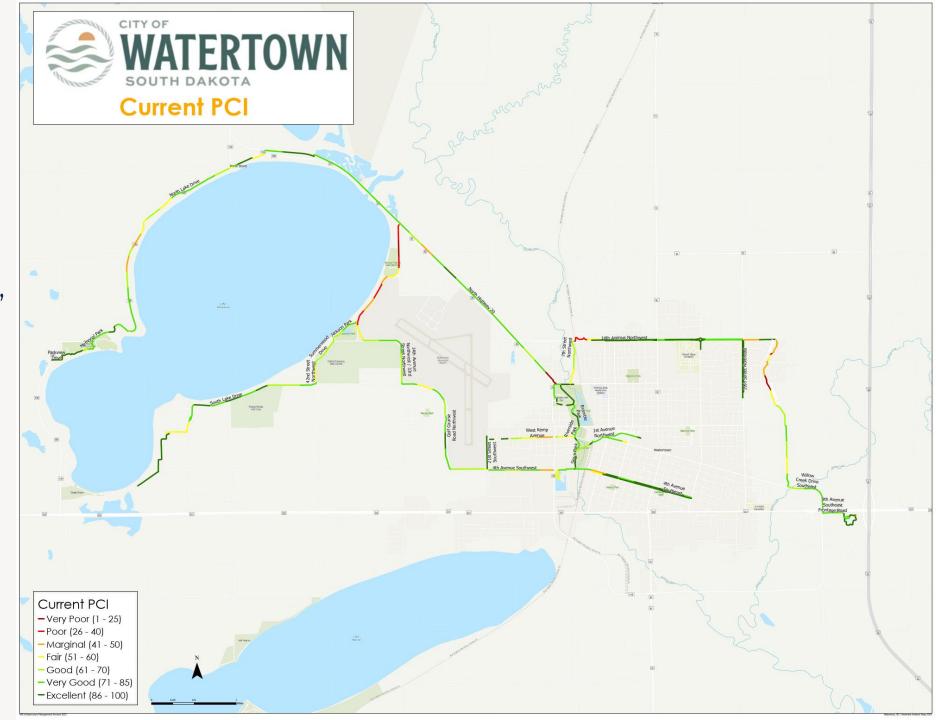


6	GISID	Direction	Street Number	Block Number	On Street	FunCL Code	Functional Class	Pavetype Code	Pavetype	Pvmnt Width (ft)	Pvmnt Length (ft)	Add Area (yd2)	Pvmnt Area (yd2)	IRI (mm/m) Deflection Results	Rutting (ACP Only)	L&T Crk / Linear Crk	Alligator Crk / Divided Slab Map Crk (Block CrkV	Cmr Brk Edge Crk /	ont span Distortions / Faulting	Bleeding / Polished Agg	Raveling / Scaling Patches / Potholes	Surface Distress Index (SDI)	Roughness Index (RI)	Structural Index (SI) Pvmnt Condition	<u>د</u> ۲	(mm/dd/yyyy)	Strength Code	Strength Kating Condition Rating	LADD	NLAD	Bon Index	1 1000 F	City of Watertow and PCC Performa	m, SD	
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		Eastbound Eastbound	1010	2	14th Avenue Northwest	1	Trail	2	Concrete	5.8	32	20	37	0.0 0	10.0	- 5. r - 10. 0	10.0 1	0.0 10.0	0 10.0	10.0	10.0 10.0		100 100	60 10		H2023		ing rai Iod Excell		0	۹		ADP Cane - 3 ADP Cane - 4		
		Eastbound	1010	4	14th Avenue Northwest	1	Trail	1	Asphalt	5.9	1,000	56	1.167	0.0 0	10.0	9.1	10.0 1	0.0 10.0		10.0	10.0 10.0		100	60 9		W2023		lod Excell		7			ADP Care - 5		
		Eastbound	1010	5	14th Avenue Northwest	i	Trail	i	Asphalt	5.9	1,000	56	1,167	0.0 0	10.0	8.2	10.0 1	0.0 10.0		10.0	10.0 10.0	0 86	100	60 8		W2023		lod Excell		14			PDC Carve - 9		
		Eastbound	1010	6	14th Avenue Northwest	i	Trail	i	Asphalt	5.9	1,000	56	1,167	0.0 0	10.0	8.5	9.4 1	0.0 10.0		10.0	10.0 10.1		100	60 8		W2023		lod VGod		12			POD Garve - 10 POD Garve - 11		
		Eastbound	1010	7	14th Avenue Northwest	1	Trail	1	Asphalt	5.9	178	10	208	0.0 0	10.0	10.0	10.0 1	0.0 10.0	0 10.0	10.0	10.0 10.0	0 100	100	60 10		W2023		lod Excell		ō			POD Carve - 12 POD Carve - 13		_
6		Eastbound	1010	8	14th Avenue Northwest	1	Trail	1	Asphalt	7.5	1,000	56	1,167	0.0 0	9.8	8.5	10.0 1	0.0 10.0	0 10.0	10.0	9.2 10.0	0 82	100	60 8		W2023		lod V Goo		16		-	POD Dane - 14 POD Dane - 15		
7	111	Eastbound	1010	9	14th Avenue Northwest	1	Trail	1	Asphalt	6.2	1,000	56	1,167	0.0 0	10.0	8.3	10.0 1	0.0 10.0	0 10.0	10.0	8.5 9.9	1 76	100	60 7	6 6/14	W2023	2 M	lod V Goo	od 2	22		0	Place and a second seco	_	_
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		Eastbound	1010	15	14th Avenue Northwest	1	Trail	2	Concrete	5	1 000	0	1 107	0.0 0	10.0	10.0	10.0 1	0.0 10.0	U 10.0	10.0	10.0 10.0) 100 : 48	100	60 10		W2023		lod Excell		0					
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		Eastbound Westbound	1020	1	14th Avenue Northwest	-	Trail	1	Concrete Asphalt	5.2	1,000	56	1,167	0.0 0	10.0	8.5	10.0 1	0.0 10.0	0 10.0	10.0	9.1 10.0) 83	100	60 R		H2023 H2023		iod Excell Iod VGod		17					
		Westbound Westbound	1020	2	14th Avenue Northwest	1	Trail	1	Asphalt	6.3	1,000	56	1,167	0.0 0	10.0		10.0	0.0 10.0			9.1 10.1		100	60 8		H2023 H2023		lod VGoo		17					
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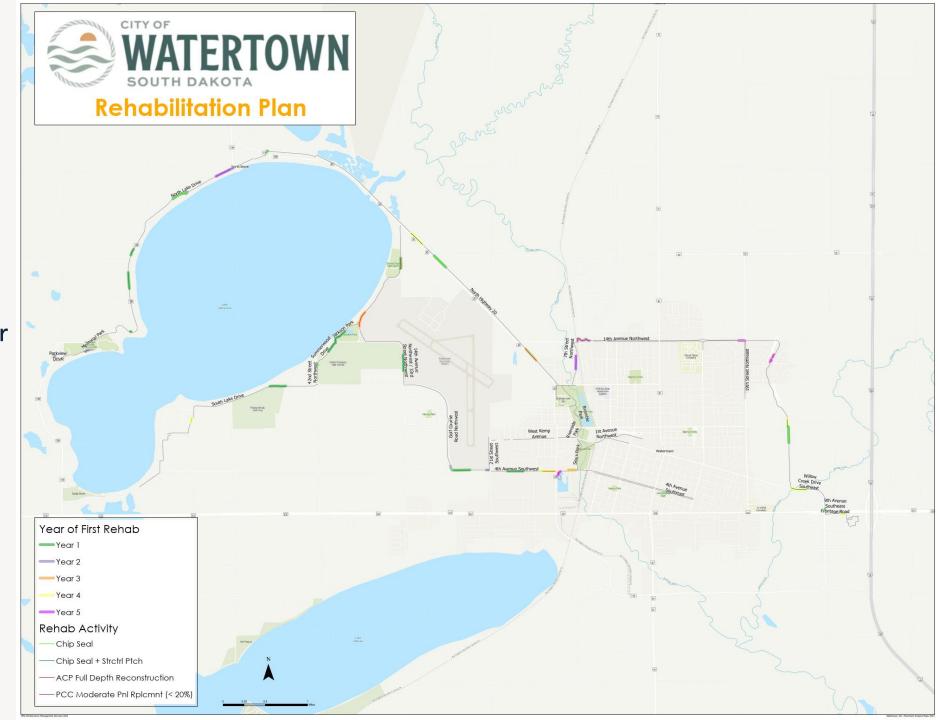
Condition

- Data is linked with Client's GIS and Asset Management Solution
- User-defined intervals, e.g. 2 m, 10 m, 100 m, segment-level



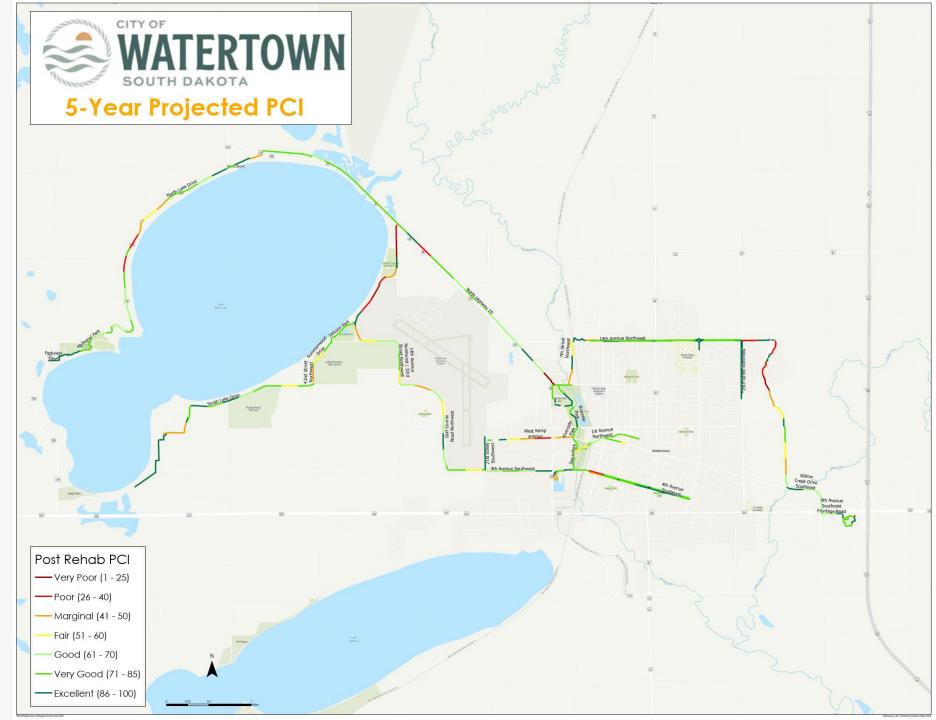
Rehabs

 5-year rehab plan based on ESA optimization and client's budget and treatment types is presented as GIS layer



Projection

• Future condition after 5 years is projected assuming the recommended rehab plan is followed



Conclusions

- Cost-effective cycle path surveys can be done with a combination of automated and manual efforts
- High degree of variation in conditions and defect types may make implementation of AI more challenging as it requires large training data sets
- Further work is required to develop or adopt metrics that are suitable for characterizing safety and comfort on cycle paths and trails
- Software that has an open architecture and is extendable can allow agencies and research institutes to develop and test algorithms more rapidly





Thank You

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